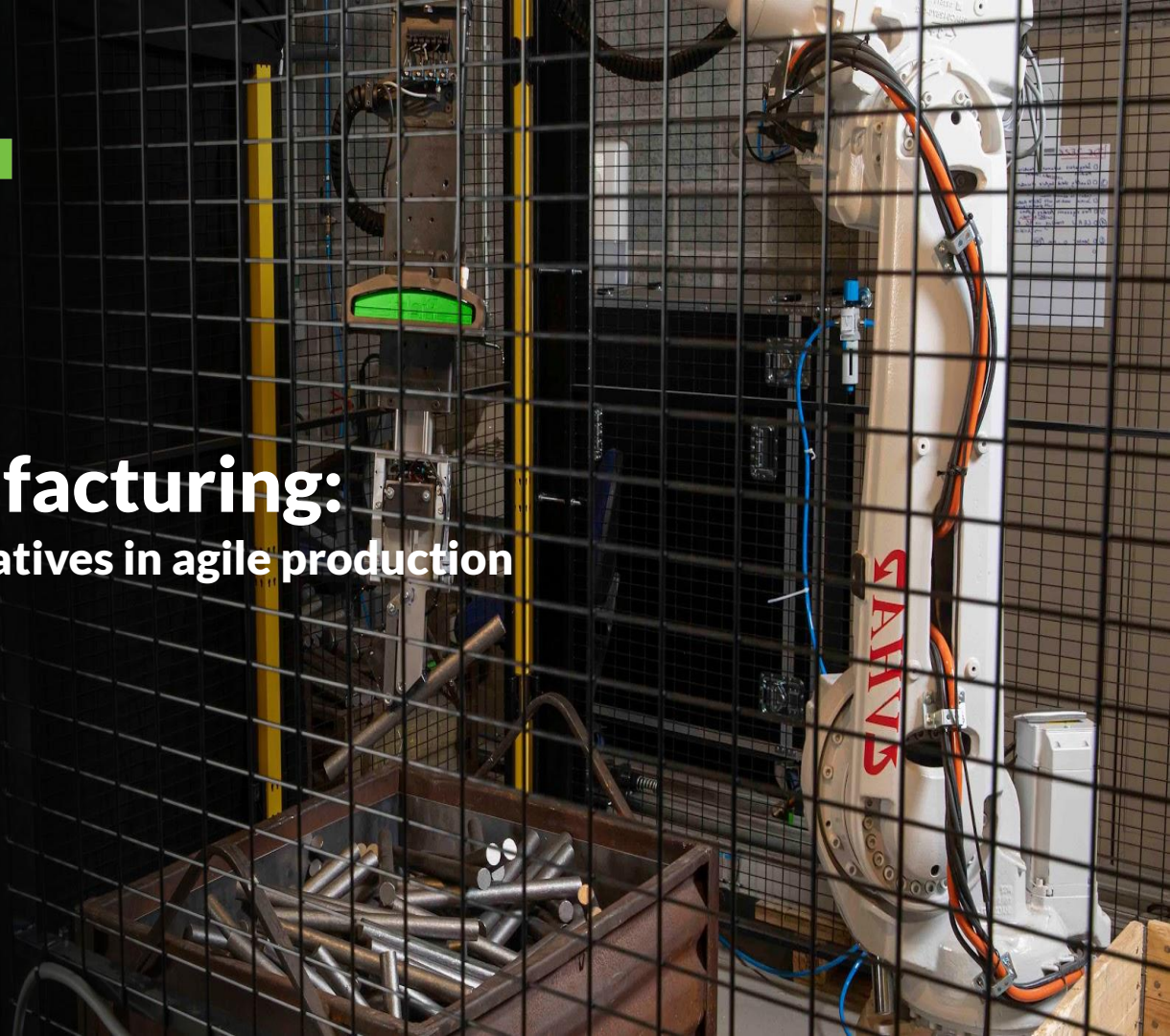


Pickit

robot vision made easy

Redefining manufacturing: Showcasing EU-funded initiatives in agile production

Timothee Habra, CTO
Sept 21 2023



Pickit - our history

2010

Robotic software
development



Google



H.ESSERS

BOSCH

ABB

ENGIE

2016

Pioneer in Plug & Play
3D Vision for robots



2023

Deployment: +1000 systems
+6 years production



Our products

Key Benefits

Pickit

all work with

UNIVERSAL ROBOTS

KUKA

TM

YASKAWA

OMRON

▲ HYUNDAI

Doosan Robotics

ABB

STÄUBLI

neuromeka

NACHI

FANUC

Our cameras

The **Pickit 3D cameras** are structured light cameras with predictable accuracy. Different versions trade resolution for price and can all be mounted fixed as well as on-robot.



Our software

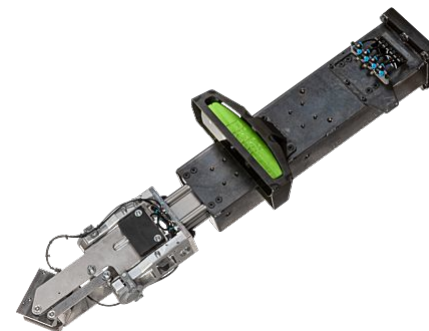
The Pickit platform combines **performances** with **ease-of-use** in an unprecedented way: Pickit applications are configured (not programmed).

This software integration platform has built-in remote and cloud support tools.

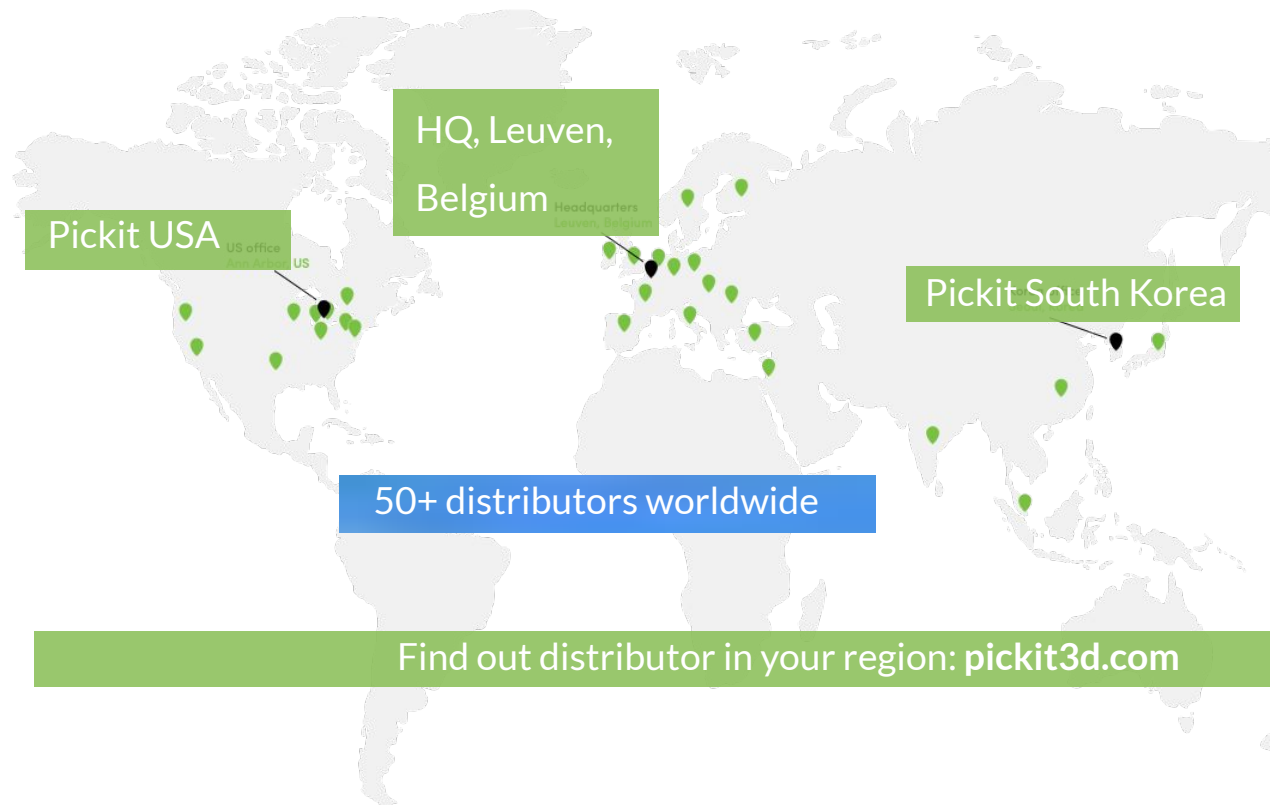


Our grippers

Building on our patented adaptive tooltip design, the **Pickit grippers** maximize the ability to pick parts from the bin. All necessary compliance and sensors to pick successful are integrated.



Pickit - our network



Our customers

By Industry

Steel Parts



Automotive Drivelines



Consumer Products



Construction Parts



Pharmaceutical Parts and Packages



APOSTORE

Example of application: Bin Picking



[Bin picking](#)

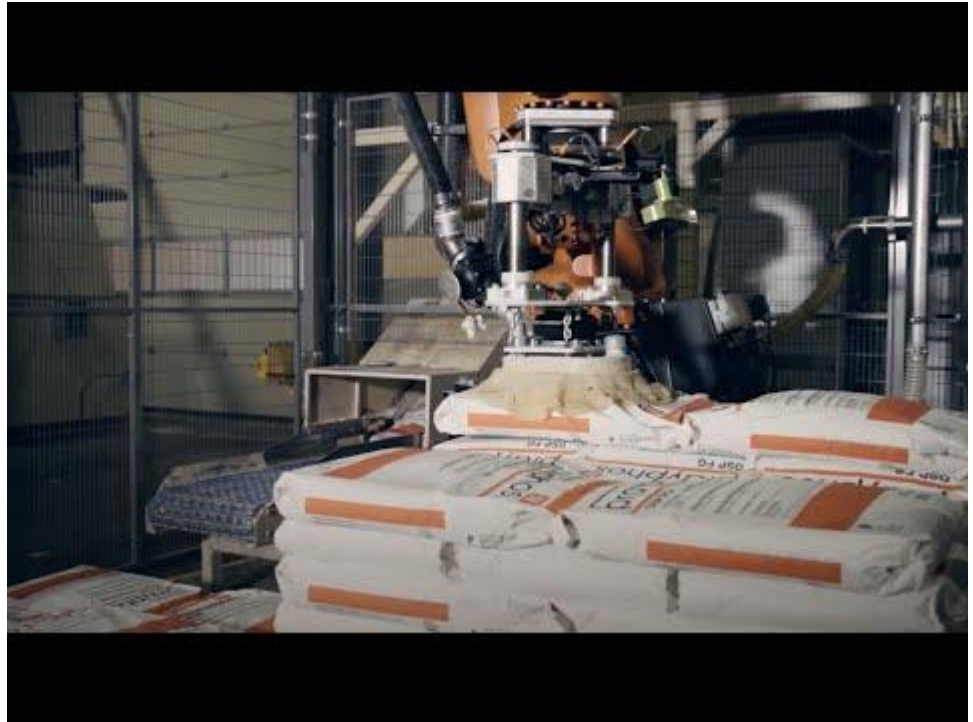


[Bin picking](#)

Depalletizing



[Boxes Depal](#)



[Bags Depal](#)

Predictable bin picking of shafts and axles



FROM DREAMS TO REALITY



SHAFTS
*Local demonstrations of
predictable bin picking*

Pickit
robot vision made easy


DELTA-TECH
GROUP
FROM DREAMS TO REALITY


aicrowd
imagine smart production


trinity
ENGAGE WITH
AGILE MANUFACTURING

 SHAFTS - Local demonstrations of predictable bin picking" is part of a sub-project that has indirectly received funding from the European Union's H2020 research and innovation programme via an Open Call issued and executed under project TRINITY (grant agreement No 825196)

[Video link](#)



Q&A